Lecture 7 Autoregressive Processes in Space

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3 Estimating Parameters

4 Testing for Spatial Autocorrelation





AR Processes in Time

• Rather than model the covariance between errors explicitly, we assumed that the errors followed an AR(*p*) process:

$$\epsilon_t = \phi_1 \epsilon_{t-1} + \dots + \phi_p \epsilon_{t-p} + \delta_t.$$

- This induced a covariance structure between the errors.
- Estimation of ϕ is easy:
 - Under the "hack" approach, you will have estimates *ϵ̂t* of the errors, and you can estimate φ by regressing *ϵ̂* on lagged versions of itself.
 - If you follow the model-based approach, optimization over φ is not difficult because Σ⁻¹_φ is banded.





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Sudden Infant Death Syndrome (SIDS) Data

```
library(spdep)
example(nc.sids)
gr.colors <- colorRampPalette(c("gray", "red"))
spplot(nc.sids, "SID74", col.regions=gr.colors(100))</pre>
```



AR processes have traditionally been used to model **lattice data** (or **areal data**), like this.

Generalizing AR Processes to Space

There are two equivalent ways to specify a temporal AR process:

• By defining the variables in terms of each other:

$$\epsilon_t = \sum_{j=1}^p \phi_j \epsilon_{t-j} + \delta_t,$$

where $\delta_t \stackrel{iid}{\sim} N(0, \tau^2)$.

• By specifying the conditional distribution:

$$p(\epsilon_t|\epsilon_{t-1},\epsilon_{t-2},...) \propto \exp\left\{-\frac{1}{2\tau^2}\left(\epsilon_t - \sum_{j=1}^p \phi_j\epsilon_{t-j}\right)^2\right\}$$

Both can be generalized naturally to space.



Generalizing AR Processes to Space

• Simultaneous Autoregression (SAR):

$$\epsilon_s = \phi \frac{1}{|N(s)|} \sum_{s' \in N(s)} \epsilon_{s'} + \delta_s,$$

where N(s) denotes the neighbors of s and $\delta_s \stackrel{iid}{\sim} N(0, \tau^2)$.

• Conditional Autoregression (CAR):

$$p(\epsilon_s | \boldsymbol{\epsilon}_{-s}) \propto \exp \left\{ -\frac{1}{2\tau^2} \left(\epsilon_s - \phi \frac{1}{|N(s)|} \sum_{s' \in N(s)} \epsilon_{s'} \right)^2 \right\}.$$

Are they the same?



Simultaneous Autoregression (SAR)

$$\epsilon_s = \phi \frac{1}{|N(s)|} \sum_{s' \in N(s)} \epsilon_{s'} + \delta_s.$$

Let W be the matrix where $W_{ij} = 1/|N(i)|$ if $j \in N(i)$ and 0 otherwise. Then, we can write the SAR model as

$$\boldsymbol{\epsilon} = \phi W \boldsymbol{\epsilon} + \boldsymbol{\delta},$$

where $\boldsymbol{\delta} \sim N(\mathbf{0}, \tau^2 I)$, or equivalently

$$(I - \phi W)\boldsymbol{\epsilon} = \boldsymbol{\delta}.$$

Therefore, for SAR, $\boldsymbol{\epsilon} \sim N(\boldsymbol{0}, \tau^2 (I - \phi W)^{-1} (I - \phi W)^{-T}).$



Conditional Autoregression (CAR)

$$p(\epsilon_s|\epsilon_{-s}) \propto \exp\left\{-\frac{1}{2\tau^2}\left(\epsilon_s - \phi \frac{1}{|N(s)|} \sum_{s' \in N(s)} \epsilon_{s'}\right)^2\right\}.$$

CAR is a bit trickier.

For time series, we could order the data and obtain the joint distribution from the conditionals:

$$p(\epsilon_1,...,\epsilon_n) = p(\epsilon_1) \cdot p(\epsilon_2|\epsilon_1) \cdot p(\epsilon_3|\epsilon_1,\epsilon_2) \cdot \ldots \cdot p(\epsilon_n|\epsilon_1,...,\epsilon_{n-1}).$$

This trick doesn't work here because spatial data don't have a natural ordering.



Conditional Autoregression (CAR)

The following result gives us the joint distribution in terms of the conditionals, up to a normalizing constant:

Theorem (Brook's Lemma)

Let $p(\epsilon) > 0$ for all ϵ . Then, for any ϵ and ϵ' :

$$\frac{p(\boldsymbol{\epsilon})}{p(\boldsymbol{\epsilon}')} = \prod_{i=1}^{n} \frac{p(\epsilon_i | \epsilon_1, \dots, \epsilon_{i-1}, \epsilon'_{i+1}, \dots, \epsilon'_n)}{p(\epsilon'_i | \epsilon_1, \dots, \epsilon_{i-1}, \epsilon'_{i+1}, \dots, \epsilon'_n)}$$

Proof.

$$\begin{aligned} \frac{p(\boldsymbol{\epsilon})}{p(\boldsymbol{\epsilon}')} &= \frac{p(\epsilon_1|\epsilon'_2, \dots, \epsilon'_n)}{p(\epsilon'_1|\epsilon'_2, \dots, \epsilon'_n)} \cdot \frac{p(\epsilon_2, \dots, \epsilon_n|\epsilon_1)}{p(\epsilon'_2, \dots, \epsilon'_n|\epsilon_1)} \\ &= \frac{p(\epsilon_1|\epsilon'_2, \dots, \epsilon'_n)}{p(\epsilon'_1|\epsilon'_2, \dots, \epsilon'_n)} \cdot \frac{p(\epsilon_2|\epsilon_1, \epsilon'_3, \dots, \epsilon'_n)}{p(\epsilon'_2|\epsilon_1, \epsilon'_3, \dots, \epsilon'_n)} \cdot \frac{p(\epsilon_3, \dots, \epsilon_n|\epsilon_1, \epsilon_2)}{p(\epsilon'_3, \dots, \epsilon'_n|\epsilon_1, \epsilon_2)} \\ &= \frac{p(\epsilon_1|\epsilon'_2, \dots, \epsilon'_n)}{p(\epsilon'_1|\epsilon'_3, \dots, \epsilon'_n)} \cdot \frac{p(\epsilon_2|\epsilon_1, \epsilon'_3, \dots, \epsilon'_n)}{p(\epsilon'_2|\epsilon_1, \epsilon'_3, \dots, \epsilon'_n)} \cdot \dots \end{aligned}$$

Conditional Autoregression (CAR)

Apply Brook's lemma to obtain $p(\epsilon)/p(\mathbf{0})$ for the CAR model:

$$\frac{p(\epsilon)}{p(\mathbf{0})} = \prod_{i=1}^{n} \frac{p(\epsilon_{i}|\epsilon_{1}, ..., \epsilon_{i-1}, 0_{i+1}, ..., 0_{n})}{p(0_{i}|\epsilon_{1}, ..., \epsilon_{i-1}, 0_{i+1}, ..., 0_{n})}$$

$$= \prod_{i=1}^{n} \frac{\exp\left\{-\frac{1}{2\tau^{2}}\left(\epsilon_{i} - \phi \sum_{j < i} W_{ij}\epsilon_{j} - \phi \sum_{j > i} 0_{j}\right)^{2}\right\}}{\exp\left\{-\frac{1}{2\tau^{2}}\left(0_{i} - \phi \sum_{j < i} W_{ij}\epsilon_{j} - \phi \sum_{j > i} 0_{j}\right)^{2}\right\}}$$

$$= \exp\left\{-\frac{1}{2\tau^{2}}\sum_{i=1}^{n} \left(\epsilon_{i} - \phi \sum_{j < i} W_{ij}\epsilon_{j}\right)^{2} + \frac{1}{2\tau^{2}}\sum_{i=1}^{n} \left(\phi \sum_{j < i} W_{ij}\epsilon_{j}\right)^{2}\right\}$$

$$= \exp\left\{-\frac{1}{2\tau^{2}}\sum_{i=1}^{n} \left(\epsilon_{i}^{2} - 2\phi\epsilon_{i}\sum_{j < i} W_{ij}\epsilon_{j}\right)\right\}$$

If W is symmetric, then $2\sum_i \sum_{j < i} \epsilon_i W_{ij} \epsilon_j = \sum_i \sum_j \epsilon_i W_{ij} \epsilon_j$, so:

$$= \exp\left\{-\frac{1}{2\tau^2}\boldsymbol{\epsilon}^T(I-\phi W)\boldsymbol{\epsilon}\right\}, \text{ so } \boldsymbol{\epsilon} \sim N(\mathbf{0},\tau^2(I-\phi W)^{-1}).$$



Comparison of SAR and CAR

• Simultaneous Autoregression (SAR):

$$\boldsymbol{\epsilon} \sim N(\boldsymbol{0}, \tau^2 (I - \phi W)^{-1} (I - \phi W)^{-T}).$$

• Conditional Autoregression (CAR). W must be symmetric,

$$\boldsymbol{\epsilon} \sim N(\boldsymbol{0}, \tau^2 (I - \phi W)^{-1}).$$

Unlike with time series, the two specifications yield different models!



Extensions

- W can be any weight matrix in general. For example, we might...
 - give immediate neighbors more weight than two-hop neighbors.
 - weight pairs depending on the distance between them.
- $\operatorname{Var}[\boldsymbol{\delta}]$ does not have to be $\tau^2 I$.
 - It is common to assume that it is diagonal with different variances τ_i^2 .
 - This is important when analyzing data aggregated by county/state, since each data point is based on a different sample size n_i .
 - In this case, we typically assume $\tau_i^2 \propto \frac{1}{n_i}$.
 - If $D = \text{diag}(\tau_i^2)$, then the variance of SAR and CAR become $(I W)^{-1}D(I W)^{-T}$ and $(I W)^{-1}D$, respectively.
 - For CAR, the requirement that *W* is symmetric needs to be changed accordingly.





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- 5 Application to the SIDS Data



Estimating ϕ

- Can we estimate ϕ by regressing ϵ_s on its neighbors?
- No! First, each observation may have a different number of neighbors.
- Even if we had regularly-spaced data where every observation has the same number of neighbors, Whittle (1954) showed that this estimator is inconsistent.



Maximum Likelihood

The log-likelihood for the CAR model is

$$-\log \det(\tau^2 (I - \phi W)^{-1}) - \frac{1}{2\tau^2} (\mathbf{y} - X\boldsymbol{\beta})^T (I - \phi W) (\mathbf{y} - X\boldsymbol{\beta}).$$

It is possible to reduce to this to a partial likelihood in just ϕ by substituting the optimal values for β and τ^2 :

$$\boldsymbol{\beta}(\phi) = (X^T (I - \phi W) X)^{-1} X^T (I - \phi W) \mathbf{y}$$

$$\tau^2(\phi) = \frac{1}{n} (\mathbf{y} - X \boldsymbol{\beta}(\phi))^T (I - \phi W) (\mathbf{y} - X \boldsymbol{\beta}(\phi)).$$

Optimizing over ϕ is a one-dimensional problem that can be solved by grid search. Note that $\phi < 1/\lambda_1(W)$ is necessary to ensure that the covariance matrix is positive-definite.



Maximum Likelihood

The log-partial likelihood is

$$-\log \det(\tau(\phi)^2 (I - \phi W)^{-1}) - \frac{1}{2\tau(\phi)^2} (\mathbf{y} - X\boldsymbol{\beta}(\phi))^T (I - \phi W) (\mathbf{y} - X\boldsymbol{\beta}(\phi)).$$

W is usually sparse. The second term can be evaluated with just a few matrix-vector multiplications involving $(I - \phi W)$, which is easy to do.

The real challenge is evaluating $\log \det(I - \phi W)$. This matrix is no longer banded. But notice that

$$\log \det(I - \phi W) = \sum_{i=1}^{n} \log(1 - \phi \lambda_i(W)),$$

so we do not need to evaluate the determinant for each ϕ we test. We just have to find the eigenvalues of W once.



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Likelihood ratio test for testing $H_0: \phi = 0$.





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Model with Number of Births

Residuals





Residuals:

Min 1Q Median 3Q Max -11.10079 -1.64522 -0.60629 1.24220 14.89254

Coefficients:

Estimate Std. Error z value Pr(>|z|) (Intercept) 0.96393971 0.66719077 1.4448 0.1485 BIR74 0.00173979 0.00010181 17.0890 <2e-16

Lambda: 0.3494 LR test value: 7.4243 p-value: 0.006435 Numerical Hessian standard error of lambda: 0.12092

```
Log likelihood: -276.4861
ML residual variance (sigma squared): 14.344, (sigma: 3.7874)
Number of observations: 100
Number of parameters estimated: 4
AIC: 560.97
```

Note that what they call "Lambda" is what we have called ϕ above.



Model with Numbers of Births and Nonwhite Births

Residuals





Residuals:

Min 1Q Median 3Q Max -11.4951 -1.6394 -0.5963 1.3032 14.0163

Coefficients:

Estimate Std. Error z valuePr(>|z|)(Intercept)1.159120540.462521422.50610.012207BIR740.000534030.000205722.59590.009433NWBIR740.003572200.000554726.43961.198e-10

Lambda: 0.091006 LR test value: 0.38216 p-value: 0.53645 Numerical Hessian standard error of lambda: 0.14599

Log likelihood: -261.2314 ML residual variance (sigma squared): 10.859, (sigma: 3.2953) Number of observations: 100 Number of parameters estimated: 5 AIC: 532.46

